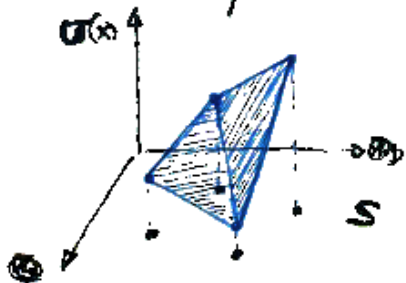


TRIANGULATION OF POINT SETS

The following problem is of practical concern:

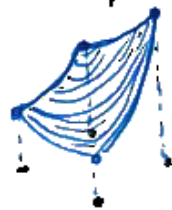
Given a point set $S \subseteq \mathbb{R}^2$ where each point $x \in S$ is associated with a weight value $\sigma(x)$. Find a way to extend the definition of σ onto \mathbb{R}^2 .

The problem is typically named "interpolation problem". There are uncountably many ways to interpolate without doubt. But we hope that σ is as simple as possible. A very appealing choice would be piecewise linear function. The illustration on the left gives an example when $|S|=4$. The four blue points correspond to the original definition



of σ , and we extended ~~them~~ them "linearly" to cover the entire region of $\text{Conv}(S)$. If we want, we could also extend further to \mathbb{R}^2 , but for clarity we didn't show it in the illustration.

Here's where the notion of triangulation comes into play. Since in general three points in the space determines a plane, we somehow have to "triangulate" the point set ~~convex~~ S if we really want to have a piecewise linear interpolation.



[It's in general impossible to interpolate linearly between 4 points in the space. So "triangulation" is the absolute way to go.]

def. triangulation of point set.

Let $S \subseteq \mathbb{R}^2$ be a finite point set. A collection \mathcal{T} of triangles ~~is~~ is a triangulation of S if

$$(1) \bigcup_{T \in \mathcal{T}} T = \text{Conv}(S)$$

$$(2) \forall T \neq T' \in \mathcal{T}, T \cap T' = \emptyset, \text{ a vertex, or an edge shared by both.}$$

$$(3) \bigcup_{T \in \mathcal{T}} V(T) = S.$$

The definition guarantees that no $T \in \mathcal{T}$ would contain a point from S in ~~the~~ its interior. (Exercise).

e.g.



If we could find a triangulation of S , then the interpolation by piecewise linear function easily follows.

Actually, it's rather painless to prove the existence of triangulations for any S .

Theorem 18.

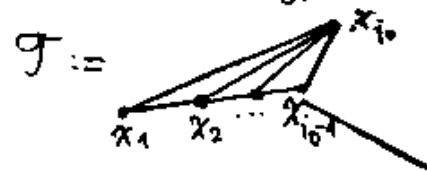
For any finite point set $S \subseteq \mathbb{R}^2$, except the very extreme case where all points in S are collinear, we could find a triangulation \mathcal{T} of S in $O(n \log n)$ time.

Proof. The algorithm incrementally builds a triangulation for S , scanning from left to right. That is, assume the points in S are ordered x_1, \dots, x_n from left to right; ~~we gradually~~ builds triangulations in step i it for the point set $\{x_1, \dots, x_i\}$ by inserting a ~~new~~ point x_i to the previously built triangulation and connect it to all points that it "sees".

Algorithm ScanTriangulate

Sort the points in S from left to right as x_1, \dots, x_n

let i_0 be the smallest index s.t. $\{x_1, \dots, x_{i_0}\}$ are non-collinear.



for $i = i_0 + 1 \dots n$ do

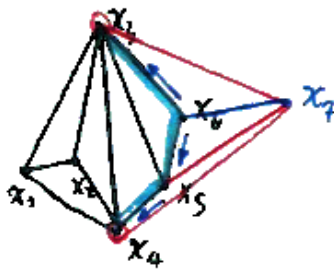
$\Gamma :=$ all points in $\{x_1, \dots, x_{i-1}\}$ that x_i could see.

$=: \{y_1, \dots, y_r\}$ in circular order

$\mathcal{T} := \mathcal{T} \cup \{ \triangle_{y_j x_i y_{j+1}} : 1 \leq j \leq r-1 \}$

We could implement the for-loop efficiently.
In the round i :

- Observe that x_i could always see x_{i-1} .
So $x_{i-1} \in \Gamma$.
- In order to obtain other elements of Γ , we start ~~at~~ walking clockwise/counterclockwise from x_{i-1} until we reach the right/left tangents. Tangency test could be done in constant time for each point ~~we~~ encountered. (Why?)



- Note that the edges that we walked through are immediately trapped after we insert x_i . So during the entire course of the for-loop, each edge is traversed at most once.
- Hence the for-loop runs in $O(n)$ time. ■

But as you could see, the triangulation constructed by the scan algorithm contains many skinny triangles. This is not only an aesthetic deficit but also a practical one: In the context of interpolation, a long and skinny triangle means a long "crease" in the piecewise linear surface, which makes the interpolation "~~less smooth~~ more edgy" and "less smooth".

There ~~are~~ ~~many~~ better ways of triangulation, and at this moment, Delaunay has a say...