

FAST FOURIER TRANSFORM*

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A polynomial $\mathbf{p} = (p_0, \dots, p_n)$ is a finite sequence of real numbers. The function $\mathbf{p}(x)$ induced by \mathbf{p} is defined by

$$\mathbf{p}(x) := \sum_{i=0}^n p_i x^i.$$

For polynomials $\mathbf{a} = (a_0, \dots, a_n)$ and $\mathbf{b} = (b_0, \dots, b_n)$, we define their *sum* as $\mathbf{a} + \mathbf{b} := (a_0 + b_0, \dots, a_n + b_n)$, and their *product* as $\mathbf{a} * \mathbf{b} := (c_0, \dots, c_{2n})$ where $c_k := \sum_{j+j'=k} a_j b_{j'}$. It is easy to verify that

$$\begin{aligned}(\mathbf{a} + \mathbf{b})(x) &= \mathbf{a}(x) + \mathbf{b}(x) \\ (\mathbf{a} * \mathbf{b})(x) &= \mathbf{a}(x) \mathbf{b}(x)\end{aligned}\tag{1}$$

for all x . So polynomial addition and multiplication are in line with the usual notions of function addition and multiplication.

Multiplying two polynomials needs $\Theta(n^2)$ time if we follow the definition plainly. Can we do it faster? To this end we need an alternative representation.

Let us fix $m + 1$ points $X = \{x_0, \dots, x_m\}$. Given an arbitrary polynomial $\mathbf{p} = (p_0, \dots, p_n)$ where $n \leq m$, we evaluate the function $\mathbf{p}(x)$ on X . This can be expressed as

$$\begin{pmatrix} \mathbf{p}(x_0) \\ \mathbf{p}(x_1) \\ \vdots \\ \mathbf{p}(x_m) \end{pmatrix} = \begin{pmatrix} 1 & x_0 & \cdots & x_0^m \\ 1 & x_1 & \cdots & x_1^m \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_m & \cdots & x_m^m \end{pmatrix} \begin{pmatrix} p_0 \\ p_1 \\ \vdots \\ p_n \\ \mathbf{0} \end{pmatrix}\tag{2}$$

where $\mathbf{0}$ pads the vector with $m - n$ zeros. The van der Monde matrix in the middle is invertible as x_0, \dots, x_m are distinct. Hence (p_0, \dots, p_n) and $(\mathbf{p}(x_0), \dots, \mathbf{p}(x_m))$ uniquely determine each other, and we shall call them the *standard* and *functional* representations, respectively, of the same polynomial \mathbf{p} .

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In the functional representation, polynomial product becomes point-wise product; see (1). This suggests the following method for computing $\mathbf{a} * \mathbf{b} =: \mathbf{c}$.

- Fix $m := 2n$ and distinct points x_0, \dots, x_m .
- Convert \mathbf{a} and \mathbf{b} to functional representations $(\mathbf{a}(x_0), \dots, \mathbf{a}(x_m))$ and $(\mathbf{b}(x_0), \dots, \mathbf{b}(x_m))$.
- Multiply point-wise to obtain $(\mathbf{c}(x_0), \dots, \mathbf{c}(x_m))$, the functional representation of \mathbf{c} .
- Convert \mathbf{c} back to its standard representation.

The “multiply” step costs merely $\Theta(n)$ time. Next we will show how to implement the conversions in $\Theta(n \log n)$ time.

We begin with the forward conversion, i.e. evaluating a polynomial $\mathbf{p} = (p_0, \dots, p_n)$ at points X . A naïve implementation would incur $\Theta(n^2)$ cost. To speed it up, let us try divide-and-conquer by breaking the evaluation at $x \in X$ into odd and even parts:

$$\begin{aligned} \mathbf{p}(x) &= \sum_{j=0}^n p_j x^j = \sum_{j=0}^{n/2} p_{2j} x^{2j} + \sum_{j=0}^{n/2} p_{2j+1} x^{2j+1} \\ &= \sum_{j=0}^{n/2} p_{2j} (x^2)^j + x \cdot \sum_{j=0}^{n/2} p_{2j+1} (x^2)^j \end{aligned}$$

Hence, denoting $\mathbf{p}_{\text{even}} := (p_0, p_2, \dots)$ and $\mathbf{p}_{\text{odd}} := (p_1, p_3, \dots)$, we have the identity $\mathbf{p}(x) = \mathbf{p}_{\text{even}}(x^2) + x \cdot \mathbf{p}_{\text{odd}}(x^2)$. This immediately leads to the following algorithm:

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fn evaluate( $\mathbf{p}, X$ )
  if  $\mathbf{p} = (p_0)$  then
    return  $(p_0, \dots, p_0)$ 
  else
     $X' := \{x^2 : x \in X\}$ 
     $\mathbf{p}_{\text{even}} := (p_0, p_2, \dots)$ 
     $\mathbf{p}_{\text{odd}} := (p_1, p_3, \dots)$ 
    return evaluate( $\mathbf{p}_{\text{even}}, X'$ ) +  $X \cdot$  evaluate( $\mathbf{p}_{\text{odd}}, X'$ )
  
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Let $T(n)$ denote the running time. Clearly we have the recursion

$$T(n) = 2T(n/2) + \Theta(m),$$

thus $T = \Theta(nm) = \Theta(n^2)$. Unfortunately it is no better than the naïve solution.

But we have a last resort. So far we did not assume any specific property of the evaluation points X . Can we craft X so that it halves in size after each recursive call?

Yes! If we set $X := \{(m+1)\text{-th roots of unity}\} \subseteq \mathbb{C}$, then after squaring, one half of the points fold into the other half, and we obtain $X' = \left\{\left(\frac{m+1}{2}\right)\text{-th roots of unity}\right\}$. With this choice, the running time recursion becomes

$$T(n+m) = 2T((n+m)/2).$$

Hence $T = \Theta(n \log n)$.

The divide-and-conquer algorithm invoked on such X is dubbed *Fast Fourier Transform*. Why is the name? Recall equation (2): the van der Monde matrix contains entries $x_j^k = \exp\left(i \cdot \frac{2\pi jk}{m+1}\right) = \cos\left(\frac{2\pi jk}{m+1}\right) + i \cdot \sin\left(\frac{2\pi jk}{m+1}\right)$, which form a Fourier basis. So evaluating p at X is equivalent to mixing the sine/cosine waves of different frequencies via coefficients p . In Fourier analysis jargon, the standard representation lives in *frequency domain*, and the functional representation lives in *time domain*.

How do we convert from functional representation back to standard representation? Let us derive an inverse formula based on equation (2). We claim that, with our choice of X ,

$$\begin{pmatrix} 1 & \bar{x}_0 & \cdots & \bar{x}_0^m \\ 1 & \bar{x}_1 & \cdots & \bar{x}_1^m \\ \vdots & \vdots & \ddots & \vdots \\ 1 & \bar{x}_m & \cdots & \bar{x}_m^m \end{pmatrix} \begin{pmatrix} 1 & x_0 & \cdots & x_0^m \\ 1 & x_1 & \cdots & x_1^m \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_m & \cdots & x_m^m \end{pmatrix} = (m+1) \cdot I$$

where the bars denote complex conjugate. Indeed, we calculate the result at cell (j,k) by

$$\begin{aligned} \sum_{\ell=0}^m \bar{x}_j^\ell \cdot x_k^\ell &= \sum_{\ell=0}^m \exp\left(-i \cdot \frac{2\pi j \ell}{m+1}\right) \cdot \exp\left(i \cdot \frac{2\pi \ell k}{m+1}\right) \\ &= \sum_{\ell=0}^m \exp\left(\frac{2\pi \ell i}{m+1} \cdot (k-j)\right). \end{aligned}$$

If $j=k$ then the result is $m+1$. Otherwise, the summands rotate around the unit circle in the complex plane and cancel each other, so we get a zero.

With the claim we derive

$$(m+1) \cdot \begin{pmatrix} p_0 \\ p_1 \\ \vdots \\ p_n \\ \mathbf{0} \end{pmatrix} = \begin{pmatrix} 1 & \bar{x}_0 & \cdots & \bar{x}_0^m \\ 1 & \bar{x}_1 & \cdots & \bar{x}_1^m \\ \vdots & \vdots & \ddots & \vdots \\ 1 & \bar{x}_m & \cdots & \bar{x}_m^m \end{pmatrix} \begin{pmatrix} \mathbf{p}(x_0) \\ \mathbf{p}(x_1) \\ \vdots \\ \mathbf{p}(x_m) \end{pmatrix}.$$

Now comes the punchline. If we pretend $(\mathbf{p}(x_0), \dots, \mathbf{p}(x_m))$ as a polynomial, then $(m+1) \cdot (p_0, \dots, p_n, \mathbf{0})$ is exactly its evaluation at points $\bar{x}_0, \dots, \bar{x}_m$. Since $\{\bar{x}_0, \dots, \bar{x}_m\} = X$, we can recover all information by just calling $\text{evaluate}((\mathbf{p}(x_0), \dots, \mathbf{p}(x_m)), X)$!